

Math 511

Q5/ $B_1 = [x, 1]$ $B_2 = [2x-1, 2x+1]$ in P_2

$B_1 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ $B_2 = \begin{bmatrix} 2 & 2 \\ -1 & 1 \end{bmatrix}$ ← x's
← const.

a) from B_2 to B_1 $\Sigma_{B_1, B_2} = B_1^{-1} B_2 \Sigma_{B_2}$

transition matrix is $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 2 & 2 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ -1 & 1 \end{bmatrix}$

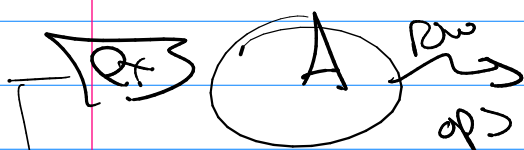
b) from B_1 to B_2

transition matrix is $\begin{bmatrix} 2 & 2 \\ -1 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} ? & ? \\ ? & ? \end{bmatrix}$

3.6 #6 $Ax = b$ if b is in col. space of A ...

→ we know we have a soln (1 or ∞ ?)

... col. vectors of A are linearly dep.



$U = \begin{bmatrix} 1 & 2 & 0 & 3 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$

$u_{12} = 2u_{11}$

$u_{14} = 3u_{11} + u_{13}$

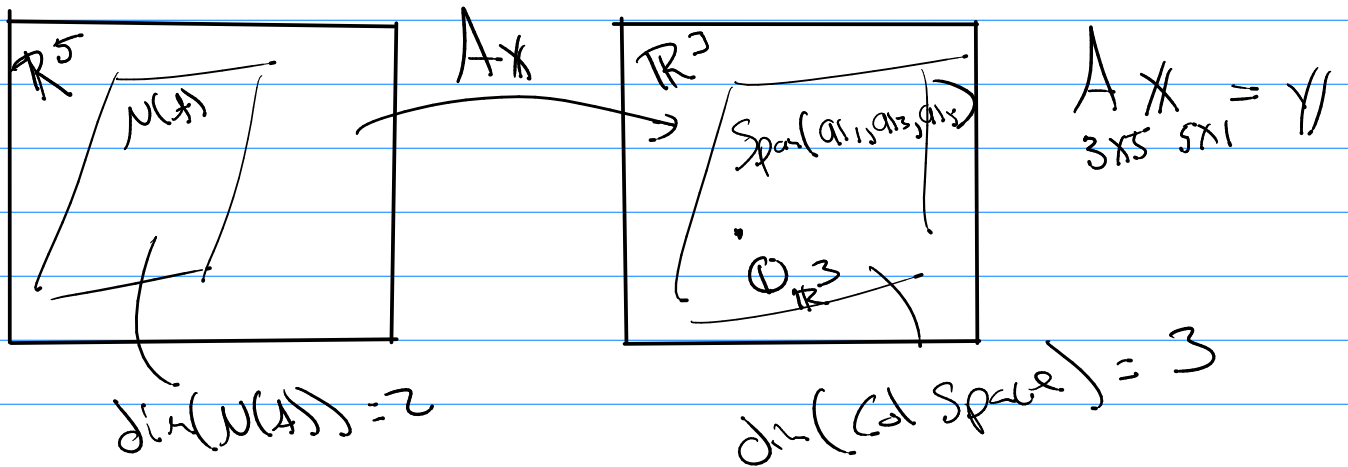
$a_{12} = 2a_{11}$

$a_{14} = 3a_{11} + a_{13}$

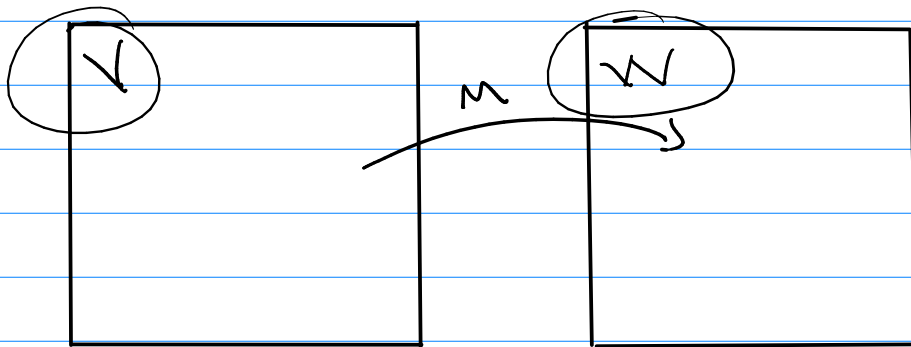
linear dep. eqn's means you have free vars.

→ ∞ Soln's

Note: A is 3×5 $\xrightarrow[\text{ops}]{\text{row}}$ $U = \begin{bmatrix} 1 & 2 & 0 & 3 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$



Ch 4



M is a mapping from V to W
 $M(v) = w$
 $v \in V, w \in W$

Ex
 \int mappings

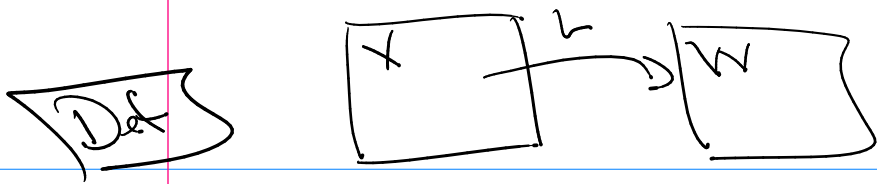
$x^2 + 2x \xrightarrow{M = \text{deriv}} 2x + 2$
 $2x + 2 \xrightarrow{\text{anti-deriv}} x^2 + 2x + C$

$2x + 2 \xrightarrow[\text{def. int.}]{\text{over } [0, 1]} 3 \text{ bc } \int_0^1 2x + 2 dx = x^2 + 2x \Big|_0^1 = 3$

Idea came from $y = Ax$ type of mappings.

→ Consider a specific type of mapping..

↳ Linear Transformation / Linear Operator on V



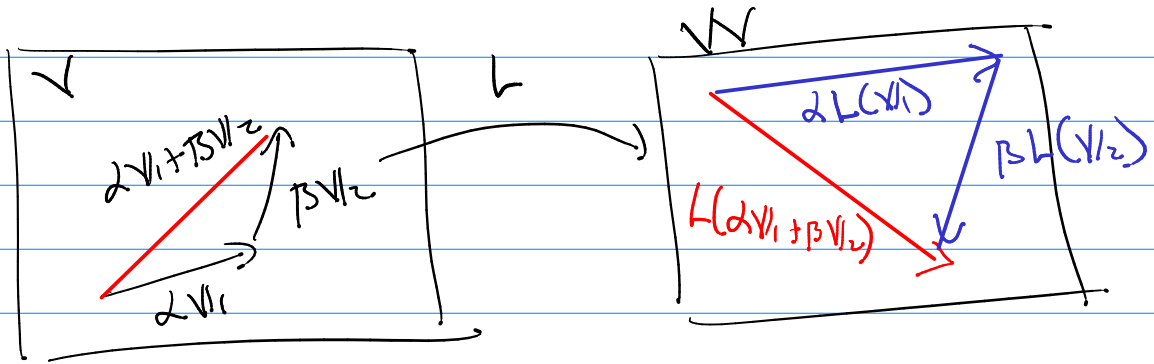
Notation: $L: V \rightarrow W$

$$L(x) = \lambda x$$

L is a Linear Transformation
(Linear Operator on V)

if given $v_1, v_2 \in V$, $\alpha, \beta \in \mathbb{R}$

$$L(\alpha v_1 + \beta v_2) = \alpha L(v_1) + \beta L(v_2)$$



Prob 4.1 given a mapping is it a linear operator?

(i) show $L(\alpha v_1 + \beta v_2) = \alpha L(v_1) + \beta L(v_2)$

or

(ii) show (i) $L(v_1 + v_2) = L(v_1) + L(v_2)$

aw

(ii) $L(\alpha v_1) = \alpha L(v_1)$

(iii) $A = \begin{bmatrix} 1 & -1 & 2 \\ 0 & 1 & 3 \end{bmatrix}$

$A: \mathbb{R}^3 \rightarrow \mathbb{R}^2$

by $y = Ax$

$x \in \mathbb{R}^3$

$y \in \mathbb{R}^2$

$\exists y = Ax$ a linear operator?

Show: (1) $A(x_1 + x_2) = Ax_1 + Ax_2$ true bc of distrib. of Matrix mult.

(2) $A(\alpha x_1) = \alpha Ax_1$ true bc of assoc. prop. of scalar matrix mult.

these are always true

for all A . So any $\mathcal{H} = Ax$ is a linear operator.

ex (1) $D: C[a,b] \rightarrow C[a,b]$

D is the 1st derivative. is D a linear operator?

Show: (1) $D(f_1 + f_2) \stackrel{?}{=} D(f_1) + D(f_2)$

(2) $D(\alpha f_1) \stackrel{?}{=} \alpha D(f_1)$

so (1) $\frac{d}{dx} [f_1(x) + f_2(x)] = f_1'(x) + f_2'(x)$

True by sum rule of deriv.

(2) $\frac{d}{dx} [\alpha f_1(x)] = \alpha \frac{d}{dx} [f_1(x)] \neq \alpha f_1(x)$

True by scalar function rule or prod. rule

\therefore deriv. is a linear operator on $C[a,b] \rightarrow C[a,b]$

Properties of $L: V \rightarrow W$

① $L(\mathbb{0}_V) = \mathbb{0}_W$

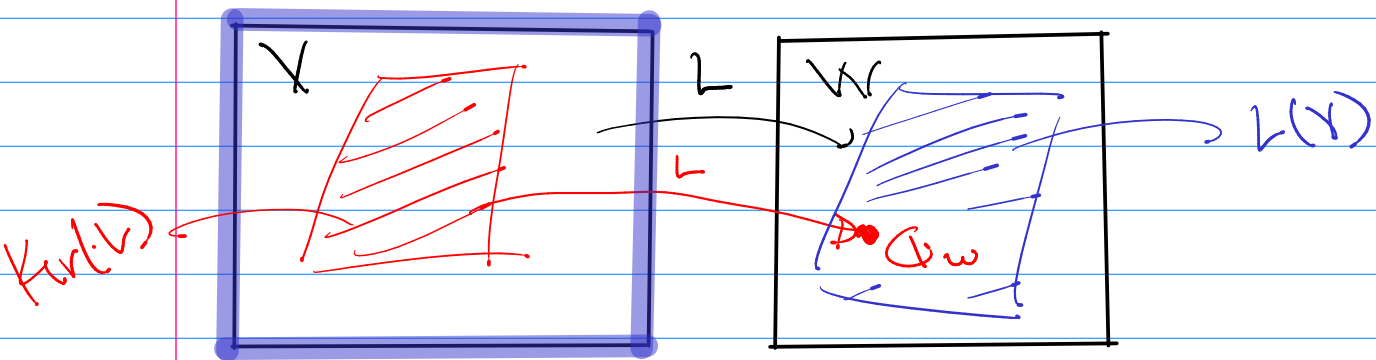
② $\alpha_i \in \mathbb{R} \quad v_i \in V$

$$L(\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n) = \alpha_1 L(v_1) + \alpha_2 L(v_2) + \dots + \alpha_n L(v_n)$$

③ $L(-v) = -L(v)$

④ Def: Identity Linear Operator

$$I(v) = v \quad \text{with} \quad I: V \rightarrow V$$



① Kernel of L , $\text{Ker}(L) = \{v \in V \mid L(v) = \mathbb{0}_W\}$

② Range of L , $L(V) = \{w \in W \mid \text{there is a } v \text{ such that } L(v) = w\}$

③ S is a subspace of V

$$L(S) = \{w \in W \mid \exists v \in S, L(v) = w\}$$