

Math 511

Q5/ $A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & & a_{2n} \\ \vdots & & & \\ a_{m1} & a_{m2} & & a_{mn} \end{bmatrix} \rightarrow u = \begin{bmatrix} \\ \\ \\ \end{bmatrix}$

lead vars = $\text{rank}(A)$
free vars = $\text{nullity}(A)$

$$\text{total vars} = n = \text{rank}(A) + \text{nullity}(A)$$

3.6 #10 a) given $\text{rank}(A) = n$ all lead vars
so \emptyset free vars.

b/c no free vars $\rightarrow M \geq n$ system is det.
or overdet.

also given $Ax = Ad$

says we have a soln.

b/c we have only 1 or 0 \rightarrow we have 1.
 $\therefore x = d$

b/c no free vars.
1 soln or 0 solns

b) $\text{rank}(A) < n \rightarrow$ free vars (says we have \emptyset solns or ∞ solns)

b/c $Ax = Ad$

says we have a soln \rightarrow ∞ solns

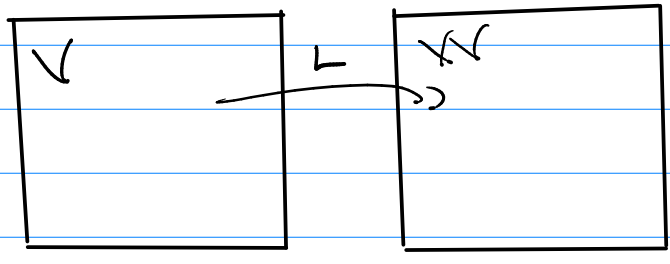
(we can show these ∞ solns by

$$Ax = Ad \rightarrow A(x-d) = 0$$

so $x-d$ is a soln.

Ch 4 Linear Transformations (Operators)

$$L: V \rightarrow W$$



$$L(x) = y$$

$$x \in V, y \in W$$

Property of L to check...

Show ① $L(\alpha_1 v_1 + \alpha_2 v_2) = \alpha_1 L(v_1) + \alpha_2 L(v_2)$

or

Show ② $L(v_1 + v_2) = L(v_1) + L(v_2)$

③ $L(\alpha v_1) = \alpha L(v_1)$

Features of Interest

① $\text{Ker}(L) = \{ v \in V \mid L(v) = 0_W \}$

② $\text{range of } L = L(V) = \{ w \in W \mid \text{there was an } v \in V \text{ such that } L(v) = w \}$

ex) $L: \mathbb{R}^3 \rightarrow \mathbb{R}^3 \quad \left(L(x) = \begin{bmatrix} x_1 \\ x_2 \\ 0 \end{bmatrix} \right) \rightarrow L\left(\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$

is L a linear transform? $v_1 = \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix} \quad v_2 = \begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix}$

① Show $L(v_1 + v_2) = L(v_1) + L(v_2)$

$$L(v_1 + v_2) = L\left(\begin{bmatrix} x_1 + x_2 \\ y_1 + y_2 \\ z_1 + z_2 \end{bmatrix}\right) = \begin{bmatrix} x_1 + x_2 \\ y_1 + y_2 \\ 0 \end{bmatrix} = \begin{bmatrix} x_1 \\ y_1 \\ 0 \end{bmatrix} + \begin{bmatrix} x_2 \\ y_2 \\ 0 \end{bmatrix} = L(v_1) + L(v_2)$$

① Show $L(2v_1) = 2L(v_1)$

$$L(2v_1) = L\begin{pmatrix} 2x_1 \\ 2y_1 \\ 2z_1 \end{pmatrix} = \begin{bmatrix} 2x_1 \\ 2y_1 \\ 0 \end{bmatrix} = 2 \begin{bmatrix} x_1 \\ y_1 \\ 0 \end{bmatrix} = 2L(v_1)$$

mm!

$$\text{Ker}(L) = \{ v \in V \mid L(v) = 0_W \}$$

$$v = \begin{bmatrix} a \\ b \\ c \end{bmatrix} \text{ all } \begin{bmatrix} a \\ b \\ c \end{bmatrix} \text{ such that } L\left(\begin{bmatrix} a \\ b \\ c \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\text{so } \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad \begin{matrix} a=0 \\ b=0 \\ c = \text{anything} \end{matrix} \quad \text{sol. } \begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix}$$

$$\therefore \text{Ker}(L) = \text{Span}\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right)$$

Range of L $L(V) = \{ w \in W \mid \text{there is } v \in V \text{ such that } L(v) = w \}$

$$\text{if } L(v) = L\left(\begin{bmatrix} a \\ b \\ c \end{bmatrix}\right) = \begin{bmatrix} a \\ b \\ 0 \end{bmatrix} = w$$

a, b, c can be any #'s

$$w = a \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$L(V) = \text{Span}\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right)$$

4.2

From 4.1 we know if A is $n \times n$
then $Ax = y$ is a linear transformation
from \mathbb{R}^n to \mathbb{R}^n

Given $L: \mathbb{R}^n \rightarrow \mathbb{R}^m$ can we find an A $n \times n$
such that $L(x) = Ax$

(ex) above we had $L(x) = \begin{bmatrix} x_1 \\ x_2 \\ 0 \end{bmatrix}$ was a linear trans.
can we find A so that

$$L(x) = Ax$$

Note: $x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}_F = \overbrace{\left(x_1 e_1 + x_2 e_2 + \dots + x_n e_n \right)}^{\text{is a linear combo}}$

$$\begin{aligned} L(x) &= L(x_1 e_1 + x_2 e_2 + \dots + x_n e_n) \\ &= x_1 L(e_1) + x_2 L(e_2) + \dots + x_n L(e_n) \\ &= \begin{bmatrix} L(e_1) & L(e_2) & \dots & L(e_n) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \end{aligned}$$

$$\begin{aligned} \text{So } L(x) &= \begin{bmatrix} L(e_1) & L(e_2) & \dots & L(e_n) \end{bmatrix} x \\ &= Ax \end{aligned}$$

$$\text{where } A = \begin{bmatrix} L(e_1) & L(e_2) & \dots & L(e_n) \end{bmatrix}$$

(ex) $L(X) = \begin{bmatrix} x_1 \\ x_2 \\ 0 \end{bmatrix}$ find A so that $L(X) = AX$

$$A = \left[L\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) \quad L\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) \quad L\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right) \right]$$

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

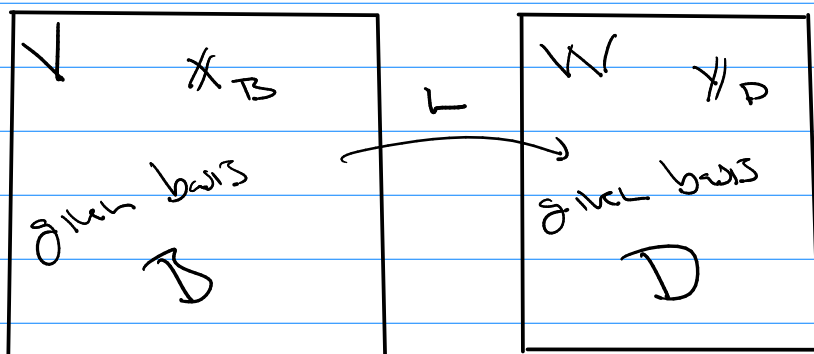
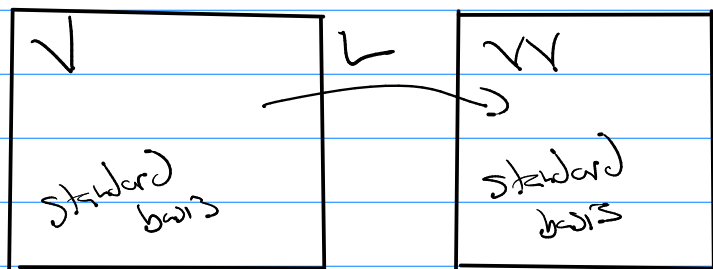
(ex) $L\left(\begin{bmatrix} 9 \\ 5 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 9 \\ 5 \\ 0 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 9 \\ 5 \\ 0 \end{bmatrix} = \begin{bmatrix} 9 \\ 5 \\ 0 \end{bmatrix}$

of orig!

Note: given $L(X)$ as a standard basis transform

$$Y = L(X) \rightarrow [Y]_E = A [X]_E$$

$$\text{and } A = [L(\phi_1) \quad L(\phi_2) \quad \dots \quad L(\phi_n)]$$



$$Y_D = \begin{pmatrix} ? \\ 0 \end{pmatrix} X_B$$

in basis standard

Use $[Y]_D = D^{-1} A [X]_B$

transform to in

standard basis

$$[Y]_D = \left(D^{-1} \underbrace{A B}_{\text{matrix of } L: V \rightarrow W} \right) [X]_B$$

matrix of $L: V \rightarrow W$

in basis B to basis D

Note: $\underbrace{A B}_P = [L(h_1) \ L(h_2) \ \dots \ L(h_n)]$

$L: \mathbb{R}^2 \rightarrow \mathbb{R}^3$

\mathbb{R}^2 basis is $B = \begin{bmatrix} 1 & 3 \\ 2 & 1 \end{bmatrix}$

$$L \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{bmatrix} x_1 \\ x_1 + x_2 \\ x_1 - x_2 \end{bmatrix}$$

\mathbb{R}^3 basis is $D = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$

$$[Y]_D = \begin{pmatrix} ? \\ ? \\ ? \end{pmatrix} [X]_B$$

$$= D^{-1} A B [X]_B$$

$$A = [L(\begin{smallmatrix} 1 \\ 0 \end{smallmatrix}) \ L(\begin{smallmatrix} 0 \\ 1 \end{smallmatrix})] = \begin{bmatrix} 0 & 1 \\ 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$[Y]_D = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}^{-1} \left(\begin{bmatrix} 0 & 1 \\ 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 2 & 1 \end{bmatrix} \right) [X]_B$$

" $\begin{bmatrix} 2 & 1 \\ 3 & 4 \\ 4 & 2 \end{bmatrix}$

