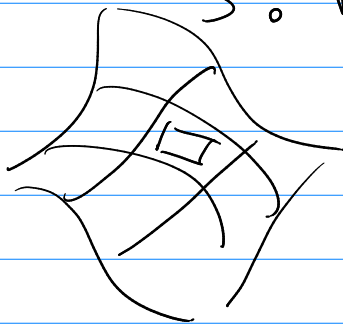


Math 344

(1D) $\int_C f ds = \int_a^b f(\vec{r}(t)) |\vec{r}'| dt$ $C: \vec{r}(t)$

(2D) $S: \vec{r}(u,v) = \langle x(u,v), y(u,v), z(u,v) \rangle$



$$\iint_S f dS = \iint_D f(\vec{r}) |\vec{r}_u \times \vec{r}_v| dA$$

\uparrow
in u,v

Application similar to line integral and vector fields

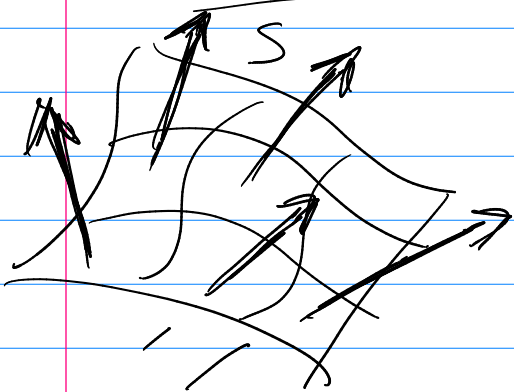
(1D) $\int_C \vec{F} \cdot d\vec{r} = \int_C (\vec{F} \cdot \vec{T}) ds$ (work)

\rightarrow Newton

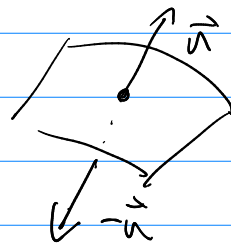
$$\int_C \vec{F} \cdot d\vec{r} = \int_C P dx + Q dy + R dz$$

$$= \int_a^b \vec{F}(\vec{r}) \cdot \vec{r}' dt$$

(2D) Surface Integrals and Vector Fields

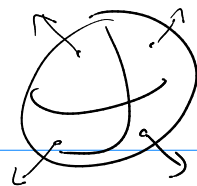


two sides: orientable surface



$$\vec{n} = \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|}$$

given solid region with S as its boundary



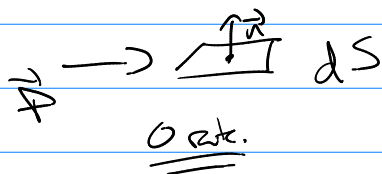
positive orientation is outward from solid region

ex Application of \vec{F} and S .

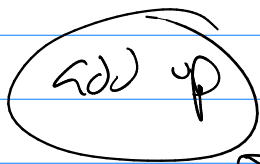
\vec{F} is fluid flow through S .



Q rate of flow through S ?



Max rate



across all S

$$\iint_S (\vec{F} \cdot \vec{n}) dS$$

rate of flow for fluid through S .

Note:

real problem to do

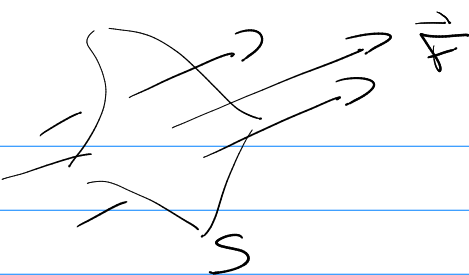
$$\vec{F} = \rho \vec{v}$$

density

velocity field

$$\iint_S (\vec{F} \cdot \vec{n}) dS = \iint_S (\rho \vec{v} \cdot \vec{n}) dS$$

In general for any \vec{F}



$\iint_S (\vec{F} \cdot \vec{n}) dS$ is called flux of \vec{F} across S .

Notation

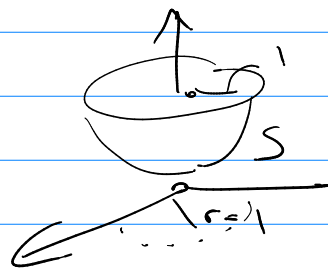
$$\iint_S (\vec{F} \cdot \vec{n}) dS = \iint_S \vec{F} \cdot d\vec{S}$$

$$= \boxed{\iint_D (\vec{F} \cdot (\vec{r}_u \times \vec{r}_v)) dA}$$

ex $\vec{F} = \langle x, y, 1 \rangle$

Flux across

$$\boxed{\begin{aligned} z &= x^2 + y^2 \\ \text{over } x^2 + y^2 &= 1 \end{aligned}}$$



$$\iint_S (\vec{F} \cdot \vec{n}) dS =$$

$S: x = u \quad \text{or } \vec{r}(u, v) = \langle u, v, u^2 + v^2 \rangle$

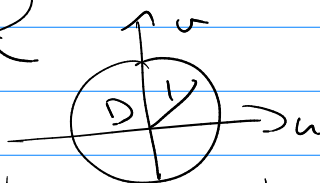
$y = v \quad \vec{r}_u = \langle 1, 0, 2u \rangle$

$z = u^2 + v^2 \quad \vec{r}_v = \langle 0, 1, 2v \rangle$

use $\iint_S (\vec{F} \cdot \vec{n}) dS = \iint_D (\vec{F} \cdot (\vec{r}_u \times \vec{r}_v)) dA$

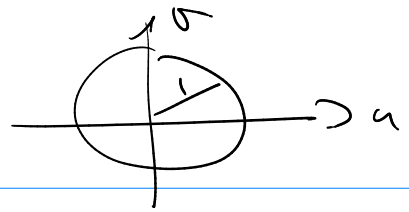
D

$\vec{F} = \langle x, y, 1 \rangle$
 $= \langle u, v, 1 \rangle$



$\vec{r}_u \times \vec{r}_v = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 0 & 2u \\ 0 & 1 & 2v \end{vmatrix} = \langle -2u, -2v, 1 \rangle$

$$S_0 \iint_S (\vec{F} \cdot \vec{n}) dS = \iint_D (1 - 2u^2 - 2v^2) dA$$



$$\text{in polar} = \int_0^{2\pi} \int_0^1 (1 - 2r^2) r dr d\theta = \underline{\underline{e\pi}}$$

Stoke's thⁿ



S is an oriented piecewise smooth surface
 ∂S is a closed piecewise smooth with pos. orientation.

$$\underline{\underline{\text{then}}} \quad \iint_S \underbrace{(\text{curl}(\vec{F})) \cdot d\vec{S}}_{\nabla \times \vec{F}} = \oint_{\partial S} \vec{F} \cdot d\vec{r}$$