

# Math 511

[Q5]

$S$  is a subspace of  $C[a, b]$ ,  $S = \text{Span}(e^x, xe^x, x^2e^x)$

$D$  is the differential operator

basis of  $S$

Idea:

$$[Y] = L([X])$$

(coord of  $Y$  in given basis) (coord of  $X$  in the given basis)

(ex) (coord)  $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

$$[X] = c_1 e_1 + c_2 e_2 + c_3 e_3$$

So for  $S = \text{Span}(e^x, xe^x, x^2e^x)$

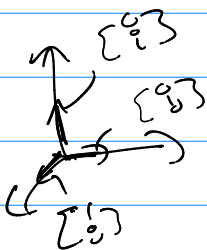
$$[X] = c_1 e^x + c_2 xe^x + c_3 x^2e^x = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} \begin{matrix} \text{multiply } e^x \\ \\ \\ \end{matrix} \begin{matrix} \\ xe^x \\ x^2e^x \end{matrix}$$

(a)  $\begin{bmatrix} -1 \\ 0 \\ 3 \end{bmatrix} = (-1)e^x + (0)xe^x + (3)x^2e^x = \underline{\underline{(3x^2-1)e^x}}$

(1)  $D(f) = \text{takes its derivative.} = f'$

(2)  $A$  of  $L$  (a linear operator)

$d_n = 3$



$$A = \left[ L\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) \quad L\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) \quad L\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right) \right]$$

Not our problem

$$\begin{aligned} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} &= e^x \\ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} &= xe^x \\ \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} &= x^2e^x \end{aligned}$$

$$\{ \} = ? e^x + ? x e^x + ? x^2 e^x$$

So  $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = e^x$

transform = derivative.  $L\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) = D(e^x) = e^x = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

$\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = x e^x$       $L\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = D(x e^x) = e^x + x e^x = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$

$\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = x^2 e^x$       $L\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right) = D(x^2 e^x) = 2x e^x + x^2 e^x = \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$

So  $\begin{array}{l|l} e^x & \xrightarrow{D} e^x \\ x e^x & \xrightarrow{D} e^x + x e^x \\ x^2 e^x & \xrightarrow{D} 2x e^x + x^2 e^x \end{array}$       $\begin{array}{l} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \\ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \\ \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} \end{array}$

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

Q Subspace  $S$  is a subspace of  $V$  is ..

3.2 #3

- ①  $S$  has  $\mathbb{0}$
- ② closure for  $x+y$
- ③ closure for  $\alpha x$

3)  $S$  is all  $2 \times 2$  diagonal matrices

①  $\mathbb{0} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$  is a diagonal matrix so  $\boxed{\text{OK}}$

②  $\begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} + \begin{bmatrix} c & 0 \\ 0 & d \end{bmatrix} = \begin{bmatrix} a+c & 0 \\ 0 & b+d \end{bmatrix}$  is diagonal so  $\boxed{\text{OK}}$

③  $2 \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} = \begin{bmatrix} 2a & 0 \\ 0 & 2b \end{bmatrix}$  is diagonal so  $\boxed{\text{OK}}$

$V = \mathbb{R}^{2 \times 2}$   
 $\left\{ \begin{array}{l} \text{all } a_{11} \\ \text{or } a_{22} \end{array} \right\}$

# Exam 2

12 probs

110pts = 100%

## 3.1 Vector Space (Axioms)

1 prob

(i) given axioms

(ii)  $\mathcal{F}$  (or  $\mathcal{I}$  is not)  $V$  with  $x+y, \alpha x \in \text{vector space}$ .  
check all 10 axioms.

(ex)  $C[a,b]$  with  $(f+g)(x) = f(x) + g(x)$  is a vector space.  
 $(\alpha f)(x) = \alpha f(x)$

(I) closure

$$(i) f \in C[a,b] \Rightarrow (\alpha f)(x) = \overbrace{\alpha \cdot f(x)}^{\text{real} \cdot \text{real} = \text{real}}$$

is a continuous function by  
closure property of reals.

$$(ii) f, g \in C[a,b]$$

$\Rightarrow (f+g)(x) = f(x) + g(x)$  is a cont. function by  
closure of addition.

(II) (A1)  $f, g \in C[a,b]$   
 $(f+g)(x) \stackrel{?}{=} (g+f)(x)$

$$(f+g)(x) = f(x) + g(x) = g(x) + f(x) = (g+f)(x)$$

etc

yes

## 3.2 Subspaces (1 prob)

(1) See above (earlier in lecture)

### 3.3 Linear Independence (2 probs)

Note:  $v_1, v_2, \dots, v_k$  in  $V$  are linear ind. when

$$\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_k v_k = 0 \quad \text{Solve for } \alpha_i$$

only  $\alpha_i = 0$  (all zero's soln)  $\rightarrow$  linear ind.

is some  $\alpha_i \neq 0$  soln (non-trivial soln)  $\rightarrow$  lin. dependent.

①  $\mathbb{R}^n$  space

②  $P_n$  space  
 $P_1(x) = 2x + 3$   
 $P_2(x) = x^2 - x$   
 $P_3(x) = 2 - x^2$   
 $P_4(x) = 1 + x + x^2$

in  $P_3$

$P_1$	$P_2$	$P_3$	$P_4$
$\begin{bmatrix} 3 \\ 2 \\ 0 \\ 1 \end{bmatrix}$	$\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$	$\begin{bmatrix} 2 \\ 0 \\ -1 \end{bmatrix}$	$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$
const	$x$	$x^2$	

### 3.4 Basis Dimension (2 probs)

① given  $v_i$  in  $\mathbb{R}^n \rightarrow$  create a basis from them.

$\dim(\mathbb{R}^3) = 3$   $\rightarrow$   $\mathbb{R}^3$

$v_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$   $v_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$   $v_3 = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$   $v_4 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$

$\uparrow$   $v_1 + v_2$        $\uparrow$   $v_2 - v_1$

$$\begin{bmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 1 \\ 1 & 1 & 2 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \end{bmatrix} \Rightarrow$$

$$\rightarrow \begin{bmatrix} \textcircled{1} & 0 & 1 & -1 \\ 0 & \textcircled{1} & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \quad \overline{v_1 \text{ and } v_2 \text{ are ind.}}$$

$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \quad \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \quad \begin{bmatrix} ? \\ ? \\ ? \end{bmatrix}$

$$\begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & \pi \end{vmatrix} = 1 \cdot 0 \cdot \pi - \pi \neq 0 \text{ so ind.}$$

## ② Basis for $P_n$

### 3.5 Change of Basis (1 prob)

① "linear for basis  $D$ , basis  $D$ "

$$D[x]_D = [B[x]_B]$$

$$[x]_D = D^{-1} B [x]_B$$

### 3.6 Row Space / Column Space (1 prob)

given  $A \rightarrow U$  find...

①  $N(A)$  with basis  $\leftrightarrow$  dimension

② row space with basis  $\leftrightarrow$  dimension

③ col space with basis  $\leftrightarrow$  dimension  $\leftrightarrow$  lin. dep. eqns

### 4.1 Linear Transformations (2 probs)

① is it a linear transform?

$$L(\alpha_1 x_1 + \alpha_2 x_2) \stackrel{?}{=} \alpha_1 L(x_1) + \alpha_2 L(x_2)$$

②  $\ker(L)$   
 $\text{range}(L)$

### 4.2/4.3 (2 probs) both $\mathbb{R}^n$

①  $L$  as a matrix in standard

$$[x]_B = A [x]_B$$

②  $L$  as a matrix for basis  $B$ .

$$[x]_B = B^{-1} A B [x]_B$$