

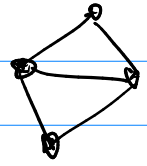
# Math 322

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10.2

Ops on graphs

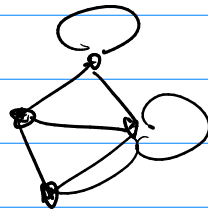
$$G = (V, E)$$



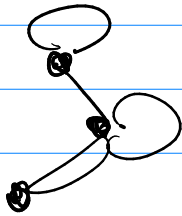
① subgraphs or induced subgraphs

② remove edges

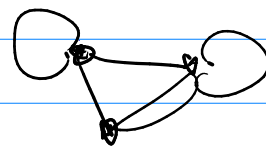
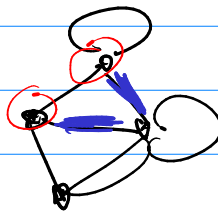
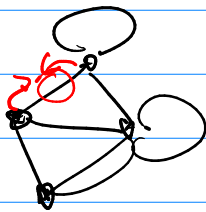
③ add edges



④ remove vertices with incident edges



⑤ edge contraction



⑥

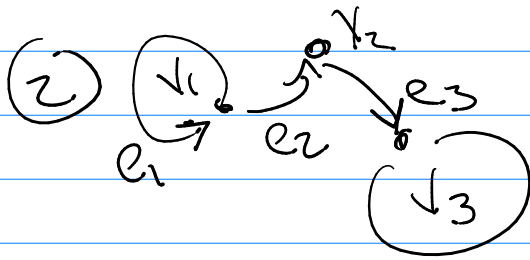
Union

$$G_1 \cup G_2 = (V_1 \cup V_2, E_1 \cup E_2)$$

# 10.3 Representing graphs and isomorphisms

## Represent Graphs

(1)  $G = (V, E)$



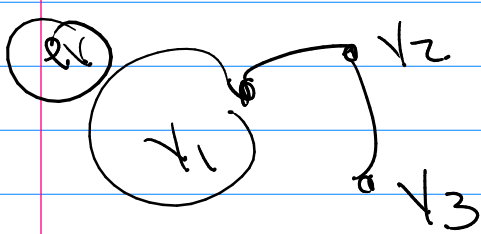
## (3) Adjacency Lists

Undirected

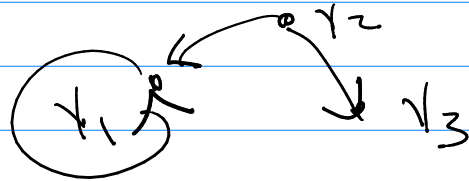
V	all $v \in V$ adj:
$v_1$	
$v_2$	
$\vdots$	
$v_n$	

Directed

$v$ (initial)	terminal
$v_1$	
$v_2$	
$\vdots$	
$v_n$	



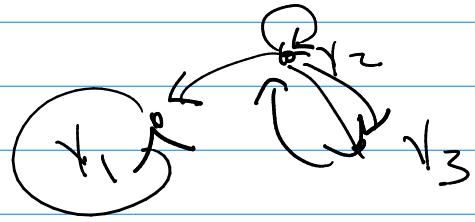
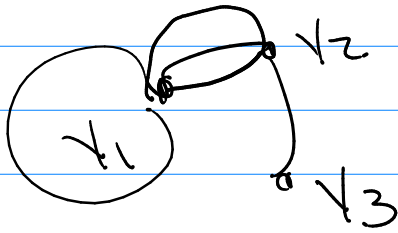
$v_1$	$v_1, v_2$
$v_2$	$v_1, v_3$
$v_3$	$v_2$



$v_1$	$v_1$
$v_2$	$v_1, v_3$
$v_3$	

④ Adj. Matrix  $M_A$  or  $A_G = \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}$

⑤



$$A_G = \begin{matrix} & v_1 & v_2 & v_3 \\ \begin{matrix} v_1 \\ v_2 \\ v_3 \end{matrix} & \begin{bmatrix} 1 & 3 & 0 \\ 3 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \end{matrix}$$

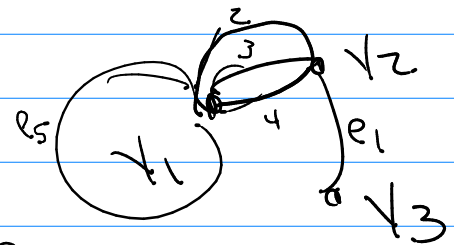
$$A_G = \begin{matrix} & v_1 & v_2 & v_3 \\ \begin{matrix} v_1 \\ v_2 \\ v_3 \end{matrix} & \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 2 \\ 0 & 1 & 0 \end{bmatrix} \end{matrix}$$

→ Sparse vs Dense  $|V|=n$

"few" edges

"lots" of edges Matrix is  $n^2$

⑤ label vertices and edges



Incidence Matrix

$$I_G = \begin{matrix} & e_1 & e_2 & e_3 & e_4 & e_5 \\ \begin{matrix} v_1 \\ v_2 \\ v_3 \end{matrix} & \begin{bmatrix} 0 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \end{matrix}$$

Note:

$$(I_G \cdot I_G^T)$$

$$\begin{matrix} v \cdot e & e \cdot v \\ 3 \times 5 & 5 \times 3 \end{matrix}$$

$$I_G^T \cdot I_G$$

$$\begin{matrix} e \cdot v & v \cdot e \\ 5 \times 3 & 3 \times 5 \end{matrix}$$

"Same"

**Def**  $G_1 = (V_1, E_1)$  and  $G_2 = (V_2, E_2)$   
are isomorphic if  $\exists f$  a bijection.

Isomorphism  $\rightarrow f: V_1 \rightarrow V_2$  that preserves edges

$$(a, b) \in E_1 \quad (f(a), f(b)) \in E_2$$

**Note**

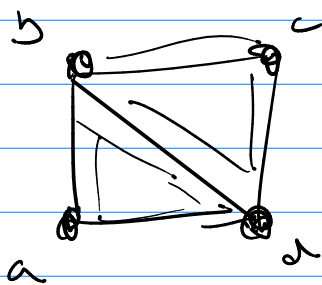
Invariants under Isomorphism

①  $|E_1| = |E_2|$  ,  $|V_1| = |V_2|$

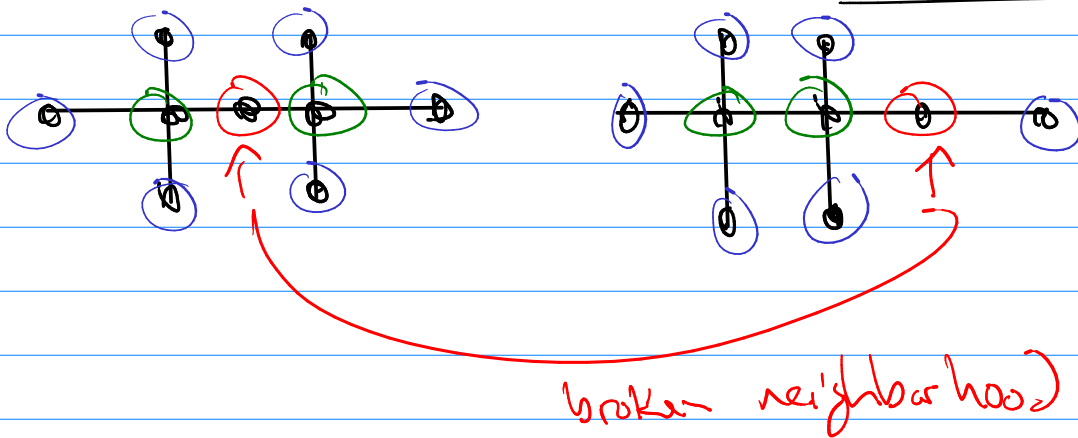
②  $\deg(v)$  must be preserved

③  $\deg(v)$  in neighborhoods must be preserved

④ paths (seq of edges) must be preserved



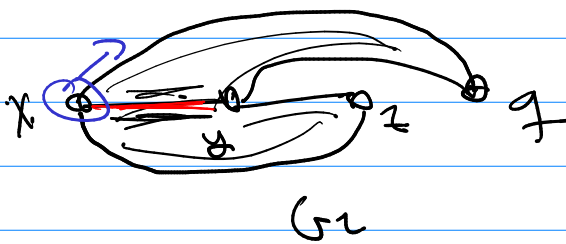
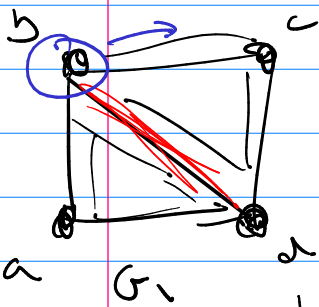
① Show not-isomorphic  $\rightarrow$  broken invariant



Not isomorphic

② Show isomorphic?

- a) no broken invariants? (maybe)
- b) find an isomorphism. (function)



$f$   
 $b \rightarrow x$   
 $c \rightarrow y$   
 $d \rightarrow z$   
 $a \rightarrow q$

c) Show Isomorphic

$$A_{G_1} = \begin{matrix} & \begin{matrix} a & b & c & d \end{matrix} \\ \begin{matrix} a \\ b \\ c \\ d \end{matrix} & \begin{bmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix} \end{matrix}$$

$$= A_{G_2} = \begin{matrix} \begin{matrix} z & x & y & q \end{matrix} \\ \begin{matrix} f(a) \\ f(b) \\ f(c) \\ f(d) \end{matrix} & \begin{bmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix} \end{matrix}$$