

Math 344

FS ————— FS

today: Review

Friday: Tech and Calculus

Q's

Monday: Exam } opens

FS ————— FS

Exam 3

12 probs @ 10pts

110pts = 100%

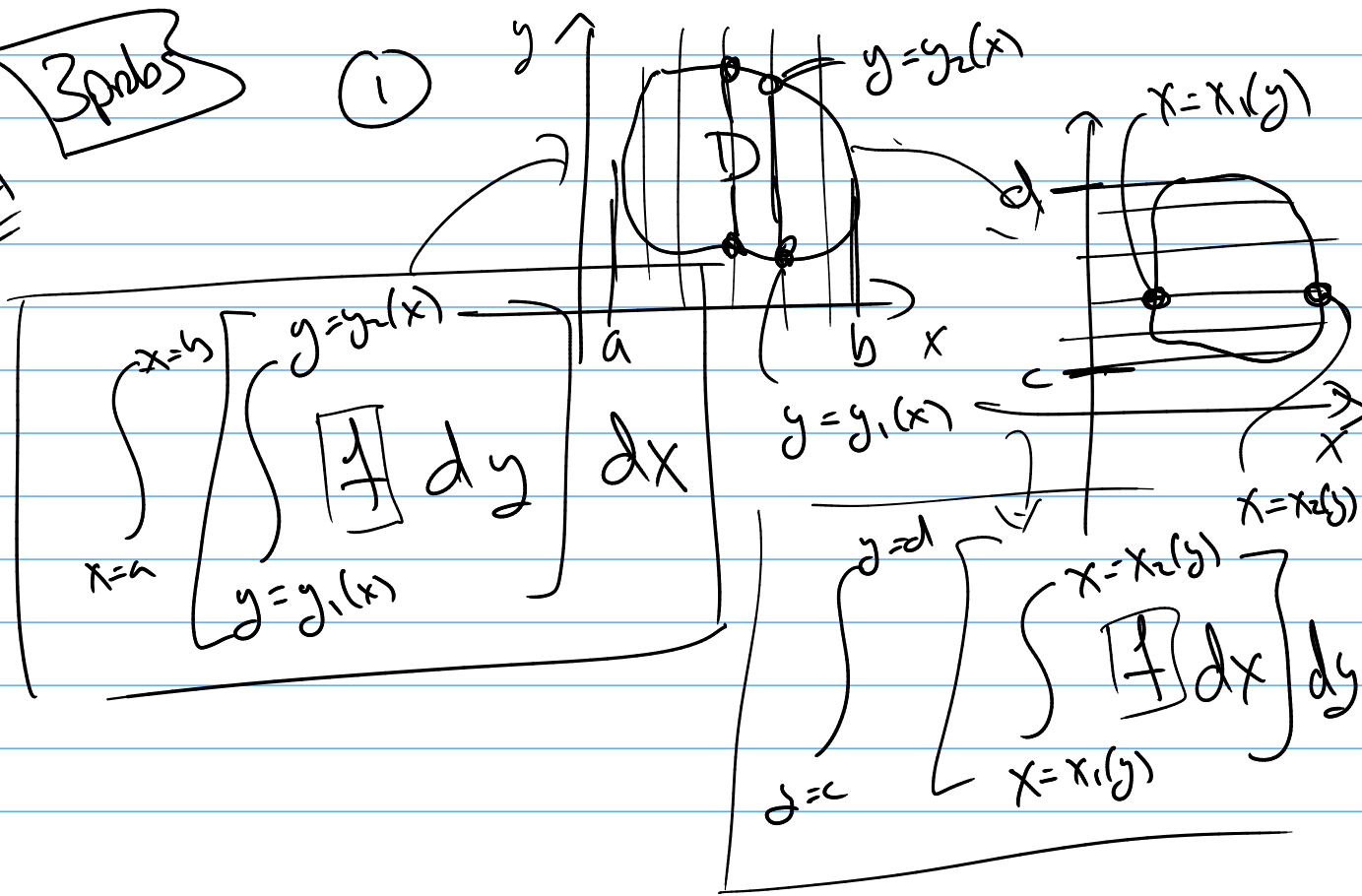
15.1 / 15.2

$$\iint_D f \, dA$$

$$dA = dx \, dy$$

3 probs

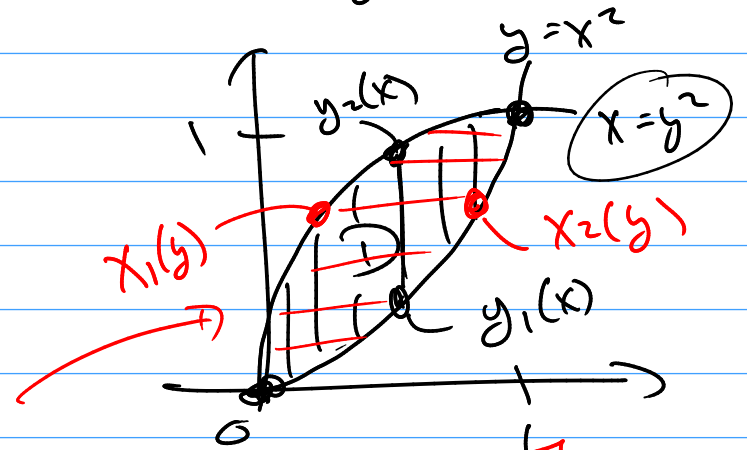
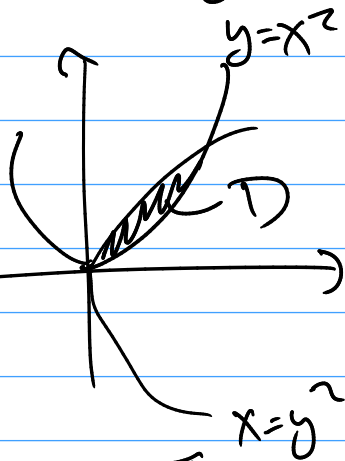
$\iint f \, dA$



(ex)

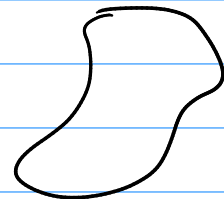
D is region between $x=y^2$ and $y=x^2$

$\iint_D f dA = ?$

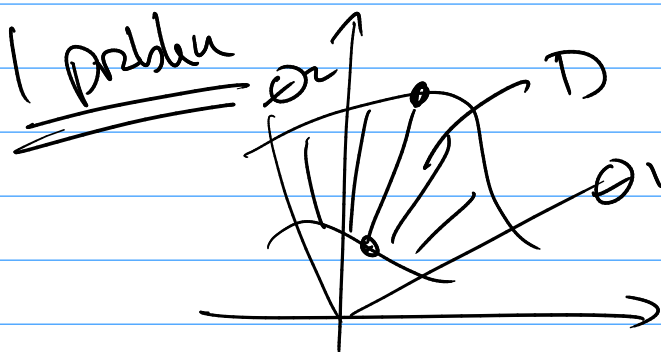


$$\int_{x=0}^{x=1} \left[\int_{y=x^2}^{y=\sqrt{x}} f dy \right] dx = \int_{y=0}^{y=1} \left[\int_{x=y^2}^{x=\sqrt{y}} f dx \right] dy$$

(2) $\iint_D f dA$ but D is 

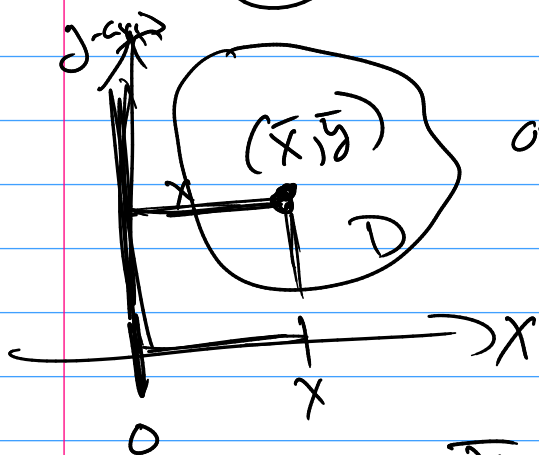
(3) $\iint_D f dA$ but D is 

15.3 $\iint_D f dA$ but $dA = r dr d\theta$ (polar)



15.4 / 15.5 Applications & $\iint_D f dA$ (2 probs)

(1) center of mass



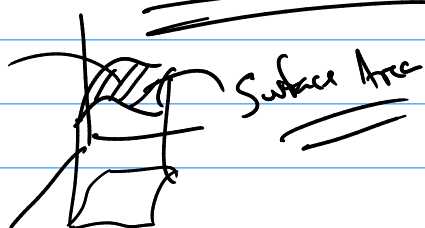
on D $\rho(x,y) = \frac{\text{mass}}{\text{area}}$ (density)

$$M = \iint_D \rho dA$$

$$\bar{x} = \frac{\iint_D x \rho dA}{M} \quad \bar{y} = \frac{\iint_D y \rho dA}{M}$$

(2) Surface Area

$$z = f(x,y)$$



$$SA = \iint_D \sqrt{1 + f_x^2 + f_y^2} dA$$

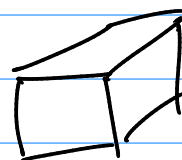
15.6 $\iiint_E f dV$

$$dV = dx dy dz$$

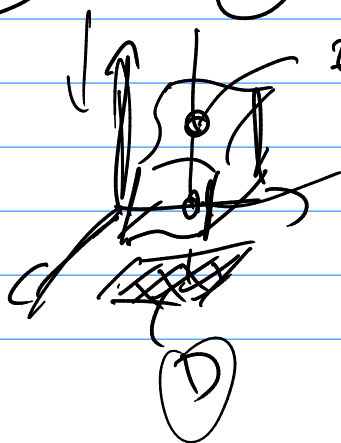
(2 probs)

(1)

E is

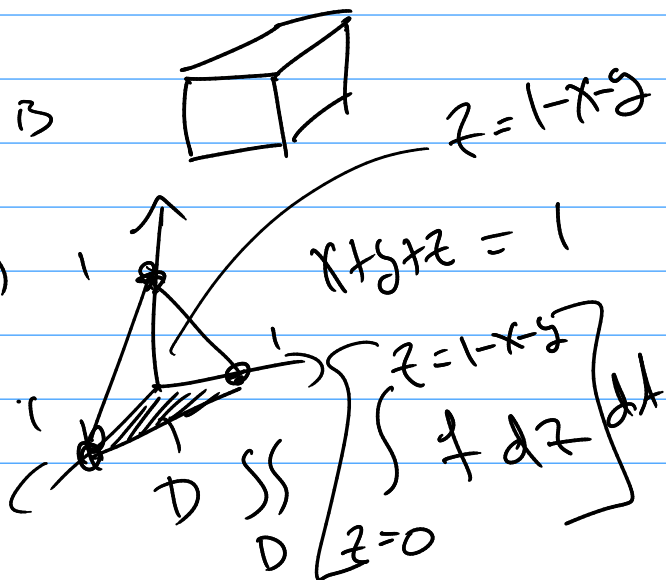


(2)



$$z_2(x,y)$$

$$z_1(x,y)$$



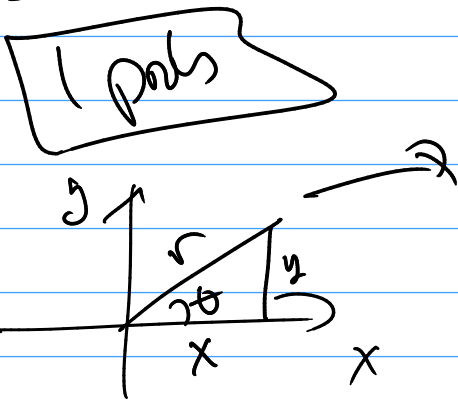
$$z = 1 - x - y$$

$$x + y + z = 1$$

$$\int_D \int_0^{1-x-y} f dz dA$$

15.7

$$dV = r dz dr d\theta \quad (\text{cylindrical})$$



$$\begin{aligned} x &= r \cos \theta & x^2 + y^2 &= r^2 \\ y &= r \sin \theta \\ z &= z \end{aligned}$$

15.8

$$\text{Spherical } dV = \rho^2 \sin \phi \, d\rho \, d\theta \, d\phi$$

$$x = \rho \sin \phi \cos \theta$$

$$y = \rho \sin \phi \sin \theta$$

$$z = \rho \cos \phi$$

$$x^2 + y^2 + z^2 = \rho^2$$

15.9

$\iiint_E f \, dV$ w/ $f(x,y,z)$ E is a x,y,z function

$$x = x(u,v,w)$$

$$y = y(u,v,w)$$

$$z = z(u,v,w)$$

$$\iiint_S f(x(u,v,w), y(u,v,w), z(u,v,w)) \left| \frac{\partial(x,y,z)}{\partial(u,v,w)} \right| \, du \, dv \, dw$$

Jacobian

2D

$$\frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} \checkmark$$

3D

$$\frac{\partial(x,y,z)}{\partial(u,v,w)} = \begin{vmatrix} x_u & x_v & x_w \\ y_u & y_v & y_w \\ z_u & z_v & z_w \end{vmatrix} \checkmark$$